* Bipolar stepper motor has two coils/two phases
* From the motor you get 4 wires connected the leads of each coil
* To operate use a microcontroller to generate a series of signals to each wire and use an h-bridge circuit to carry the signals of the microcontroller and deliver the high current
* The sequence I discovered to power the stepper motor assuming the coil 1 has leads A and B and coil 2 has leads C and D
  + ABCD
  + 1000
  + 0010
  + 0100
  + 0001
* Reverse the sequence to move the motor anticlockwise
* Using the code I wrote a single step is about 6.9 degrees
* 360 degrees is about 51 steps